

PocketBeagle Walk Through

PocketBeagle walk-through

Friendly to novices and experts alike, the Beagle experience tracks mainline u-boot, Linux and Debian development, while augmenting it to enable development to start as quickly as possible. Attendees will get started interacting with the hardware via the command-line, shell scripts, Python and JavaScript. Attendees will be walked through the configuration details for the boot configuration, pin multiplexing, USB networking and other helper scripts they should get to know. Support and development processes within the BeagleBoard.org community will be covered. Exercises will pave the way for the other workshops to dive into their topic without needing to backtrack excessively on PocketBeagle-specific details.

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- Author
 - Jason Kridner
Co-founder BeagleBoard.org, Texas Instruments Sitara apps
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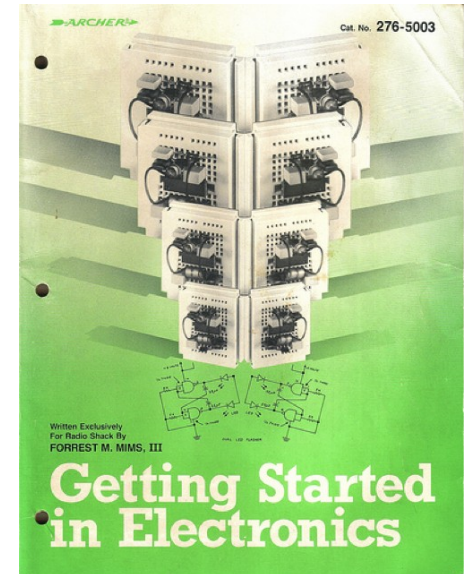
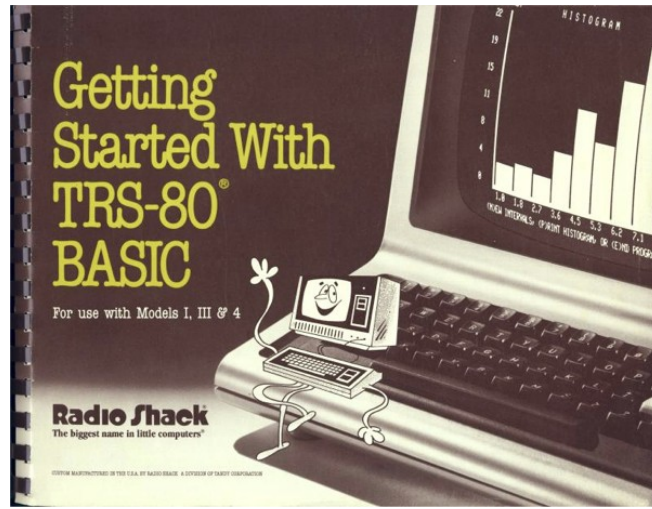
Outline

- BeagleBoard.org, PocketBeagle and BaconBits
- Developer experience
 - Command-line and shell script
 - JavaScript and Python
 - C/C++
 - C on PRUs
- Project examples
- Labs

BeagleBoard.org's objectives

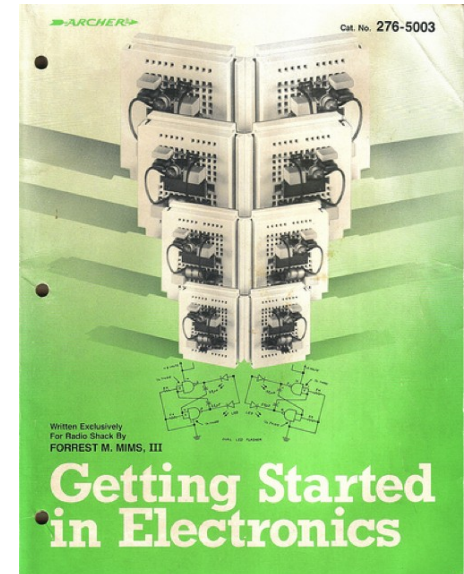
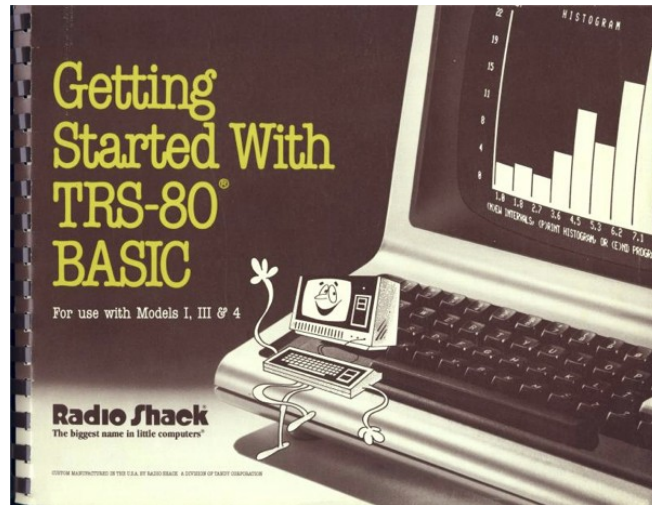
- Education
 - Design and use of open source SW/HW
 - Embedded computing
- Collaboration
 - Physical computing
 - Robotics
 - Industrial/machine controls

Inspiration from early PCs



Inspiration from early PCs

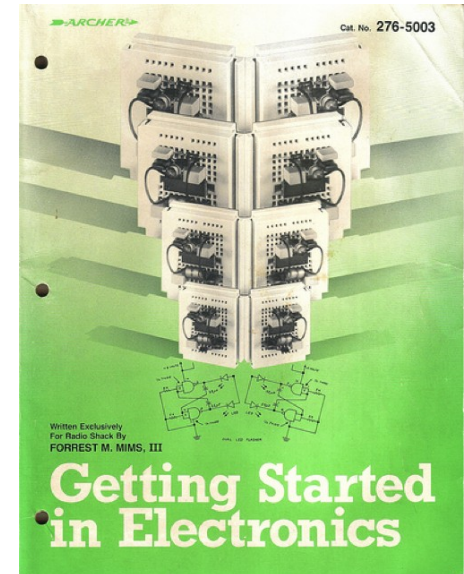
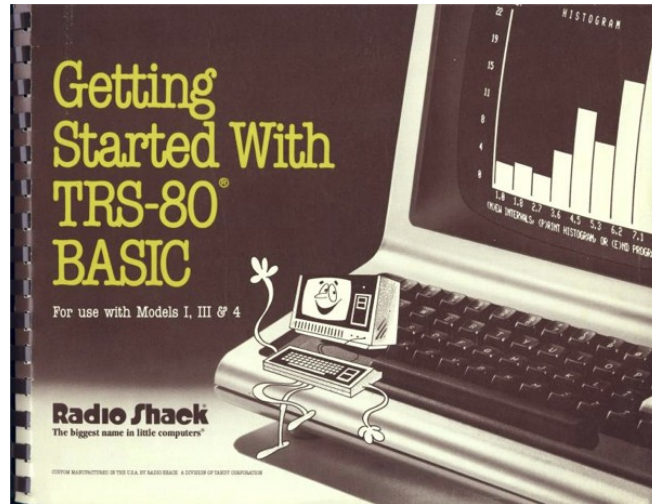
- How do people learn about embedded computers with so much ground to cover?



Inspiration from early PCs

- How do people learn about embedded computers with so much ground to cover?

- Linux keeps history
- Affordable -> hackable
- Open from boot
- High-level languages
- Motivate with hardware



Vision

- Creating with electronics should be as easy as creating a web page



Vision

- Creating with electronics should be as easy as creating a web page
- Appliances are better than applications

Vision

- Creating with electronics should be as easy as creating a web page
- Appliances are better than applications
- Open source software and hardware enable
 - Collaboration on the problem
 - Ability to understand and improve the fundamentals

Reality

- Boot-to-browser feels too limiting → booting to Debian distro
- Collaborative programming still complex → collaborate at the kernel
- Many possible development environments
 - command-line/ssh, Cloud9 IDE, node-red, pureData, SuperCollider, LabView, Matlab, Eclipse, Visual Studio, Scratch, Blockly
- Domain specific approaches
 - Machinekit/LinuxCNC, PLC, many IoT toolkits
 - Many rapid sensor approaches: capes, mikroBus, Grove/Grove Zero, PMOD
 - Many rapid build approaches: LEGO, printing/milling, Makeblock, Vex, various other aluminum kits

Approach

- Don't try to boil the ocean
 - We seek to engage the open source community
- Help where we can
 - Blue supports Grove cables
 - PocketBeagle supports mikroBus click pinout
 - Many “BeagleBoard Compatible” devices targeting specific application areas

Board history

Fanless open computer
(BeagleBoard)



\$249

Mint tin sized with industrial
peripherals (BeagleBone)



\$69

Application focused BeagleBones



\$79

Smalls mint tin sized with super-
flexible design - PocketBeagle



\$25

PocketBeagle objectives

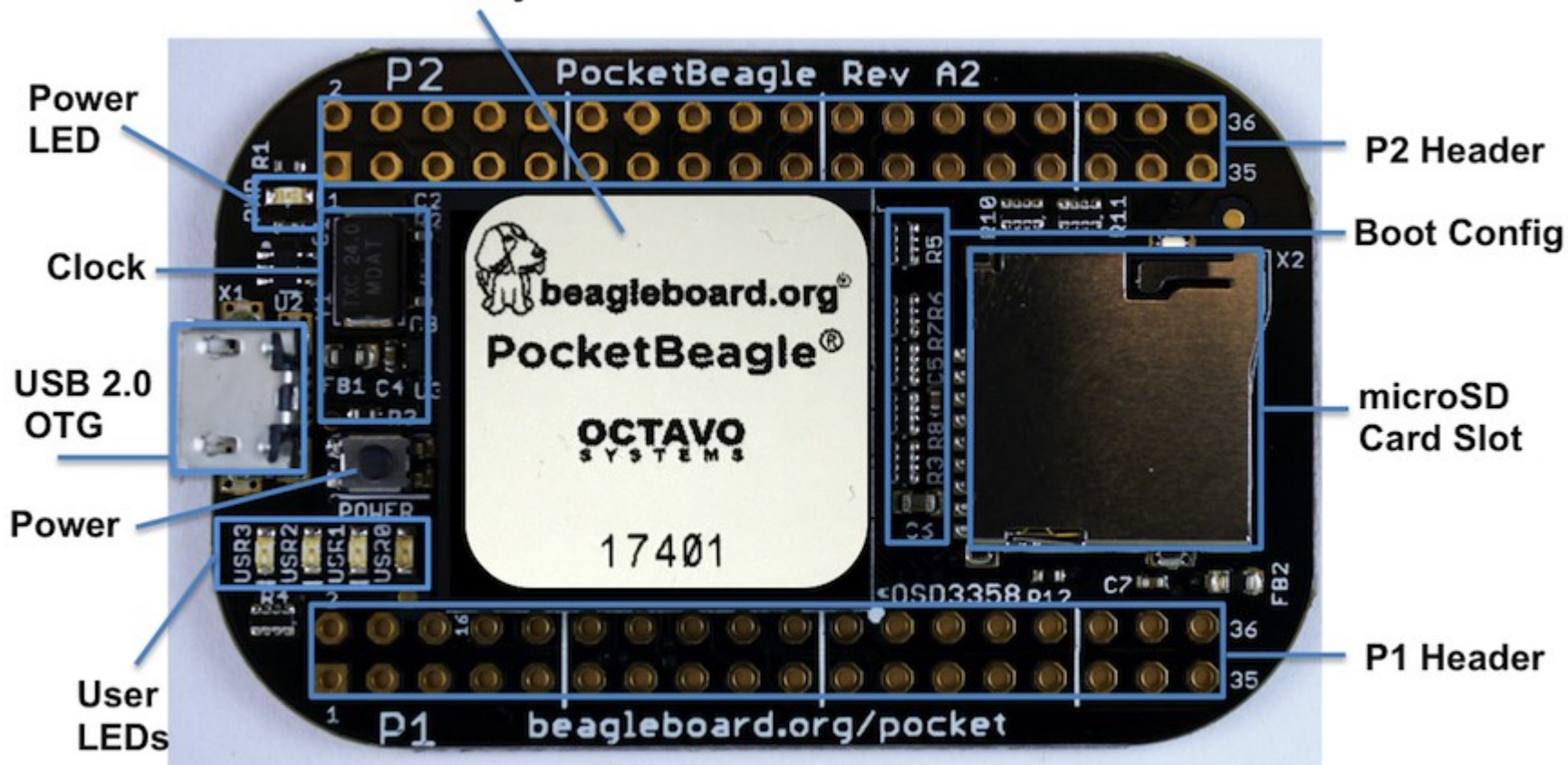
- Get simple
 - 4-layer PCB done in both Kicad and EAGLE
 - Every expansion header pin has a useful predefined mode
- Get flexible
 - USB to holes, no on-board pin consumption, no header soldered
 - Support for 2 mikroBus Click boards (over 300 already exist)
- Get small
 - Stick with mint-tin survival-kit theme, but go to “smalls” (35mm x 55mm)
- Get low cost
 - System-in-package approach has can lower build costs
 - Launched/sustainable at \$25

PocketBeagle key features

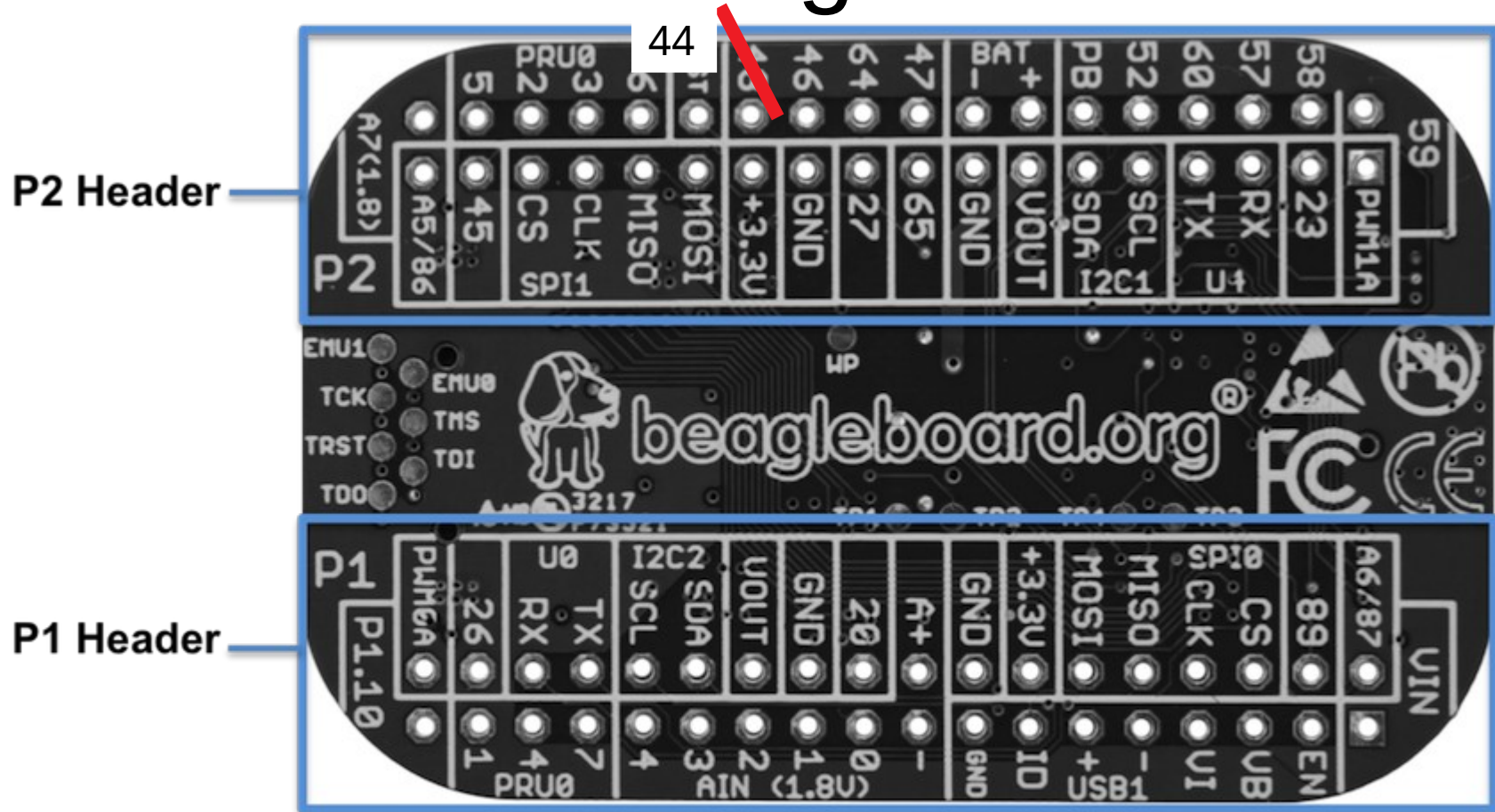
- Processing
 - 1-GHz ARM Cortex-A8 processor
 - 2x200-MHz programmable real-time units (PRUs)
 - ARM Cortex-M3 microcontroller for power and security
 - SGX530 graphics processor (OpenGL ES)
- Memory
 - 512-MB DDR3
 - 4-KB I2C EEPROM
- Interfaces
 - USB 2.0 OTG
 - microSD
- 72 expansion header pins
 - 8 analog inputs (6@1.8V, 2@3.3V)
 - 44 digital I/Os (18 enabled)
 - 3 UARTs (2 enabled)
 - 2 I2C ports
 - 2 SPI ports
 - 2 quadrature encoders accessible
 - 2 CAN bus controllers accessible
 - USB, power/reset buttons, battery/DC

PocketBeagle top

Octavo Systems OSD3358-SM



PocketBeagle bottom



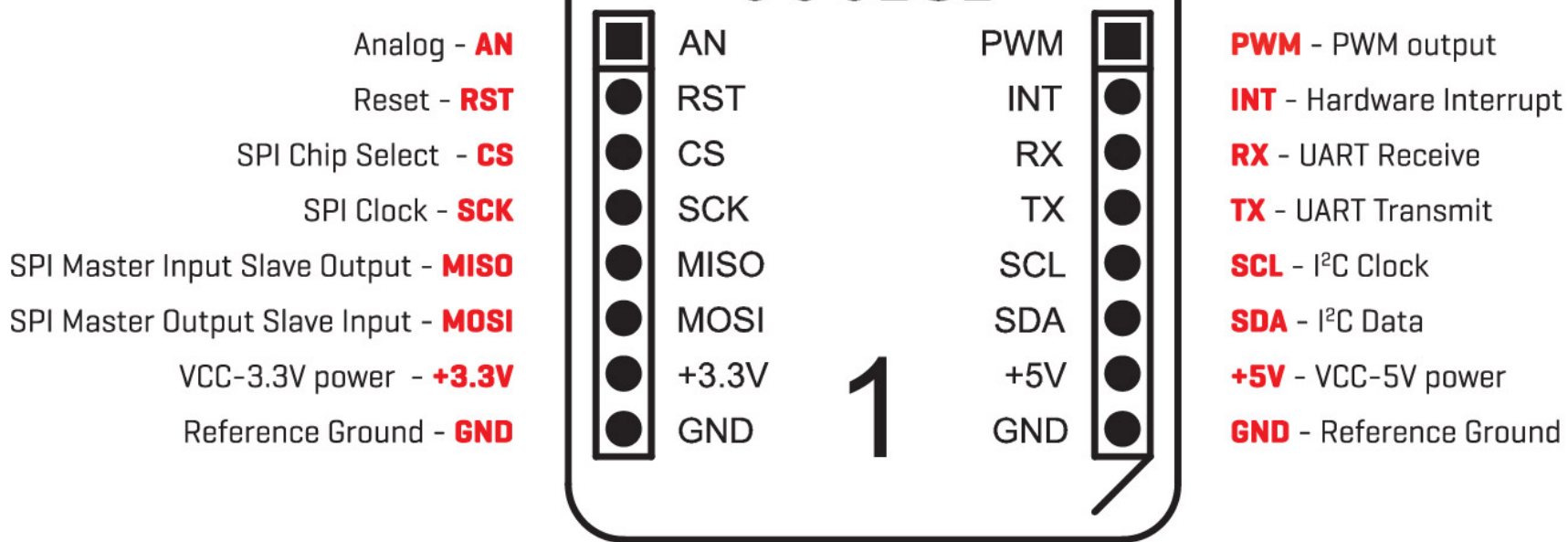
PocketBeagle expansion

PocketBeagle Expansion Headers (Rev A2a)

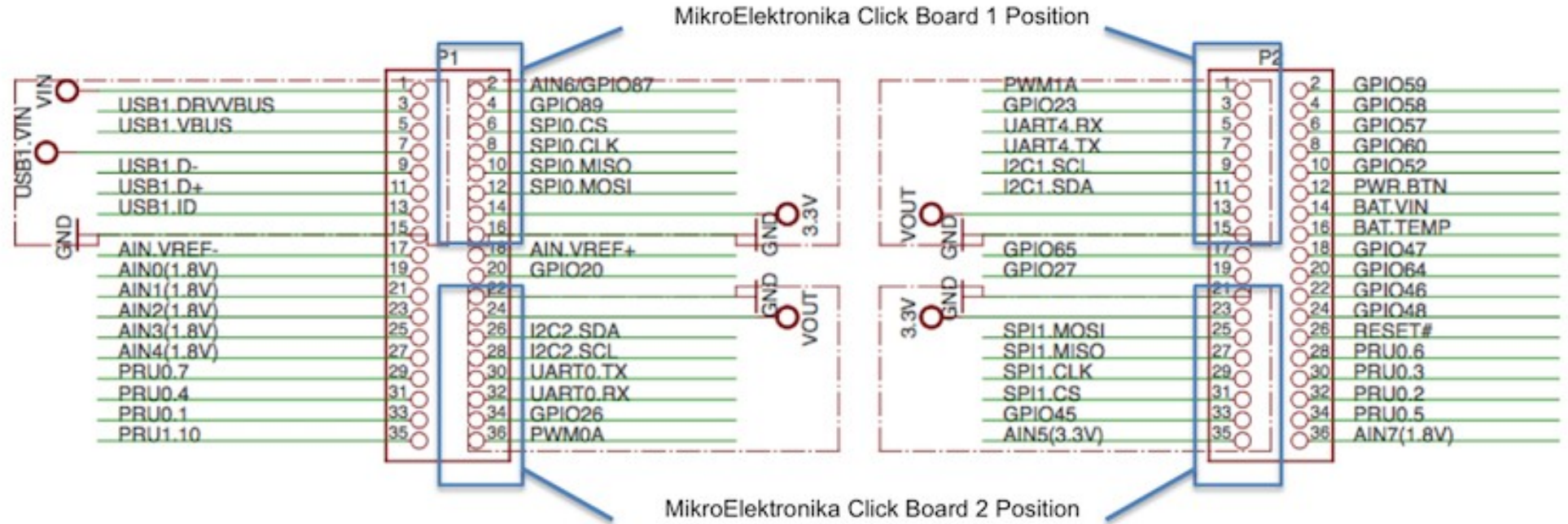
P1													
SYS		VIN	1	2	87	6		AIN 3.3V	9	PRU1			
USB1	V_EN	GPIO	109	3	4	89			11	PRU1			
USB1		VBUS	5	6	5	GPIO	CS	SPI0	TX	PRU			
		VIN	7	8	2		CLK		RX	UART2			
		DN	9	10	3		MISO		TX				
		DP	11	12	4		MOSI		RX	PRU			
		ID	13	14	3.3V		SYS						
GND		15	16	GND	SYS								
REF-		17	18	REF+	AIN 1.8V								
0		19	20	20	GPIO			16(in)	PRU0				
AIN 1.8V		1	21	22	GND	SYS							
		2	23	24	VOUT	SYS							
		3	25	26	12	SDA	I2C2	TX	CAN0				
		4	27	28	13	SCL		RX					
PRU0	7	STRB	117	29	30	43	GPIO	TX	UART0	15	PRU1		
4	QEPO	A	114	31	32	42		RX		14			
1	PWM0	B	111	33	34	26							
PRU1	10					88	35	36	110	A	PWM0	0	PRU0

P2										
PWM1		A	50	1	2	59				
PWM2		B	23	3	4	58				
UART4		RX	30	5	6	57	GPIO			
		TX	31	7	8	60				
CAN1	RX	I2C1	SCL	15	9	10	52			
	TX		SDA	14	11	12	PWR BTN	SYS		
SYS		VOUT	13	14	VIN	BAT				
GND		15	16	TEMP						
GPIO		65	17	18	47	STRB	QEPO2	15i	PRU0	
		27	19	20	64					
SYS		GND	21	22	46	IDX	QEPO2	14(in)	PRU0	
3.3V		23	24	44	A	QEPO2	14(out)	PRU0		
CAN1	RX	SPI1	MOSI	41	25	26	NRST	SYS		
	TX		MISO	40	27	28	116	IDX	QEPO0	6
PRU1	eCAP	GPIO	CLK	7	29	30	113	GPIO		
16(in)	CS		19	31	32	112				
PRU0	15(out)	QEPO2	B	45	33	34	115	B	QEPO0	5
PRU1	8	AIN 3.3V	5	86	35	36	7	AIN 1.8V		

mikroBus Click



Connecting mikroBus Clicks



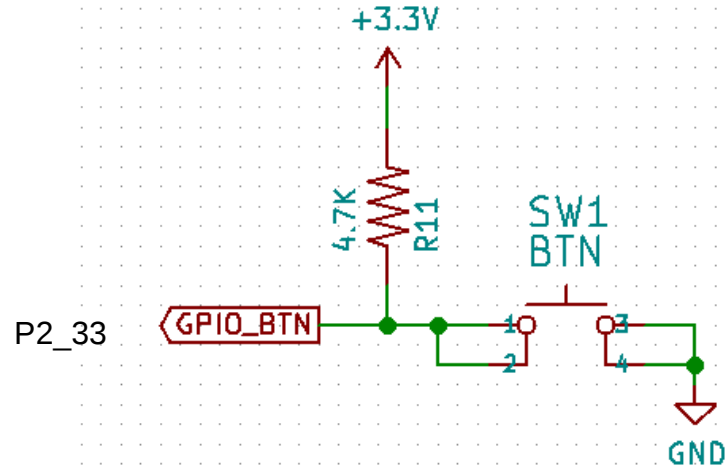
BaconBits objectives

- Designed specifically for e-ale training
- Inspired by “Bacon Cape” by Dave Anders
 - Designed for similar purpose on BeagleBone
- Provides target for common embedded interfaces
 - SPI, I2C, GPIO, PWM, ADC, USB, serial
- Avoided buying several modules

BaconBits features

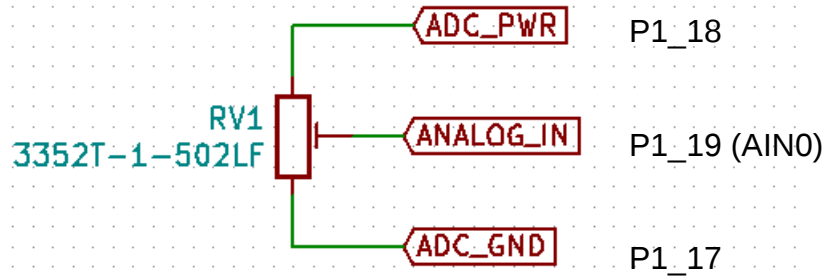
- USB-to-Serial micro B
- USB Host A with power
- Power and Reset buttons
- GPIO push button
- ADC potentiometer thumbwheel
- PWM tri-color LED
- SPI 2-digit 7-segment display
- I2C accelerometer

BaconBits GPIO button



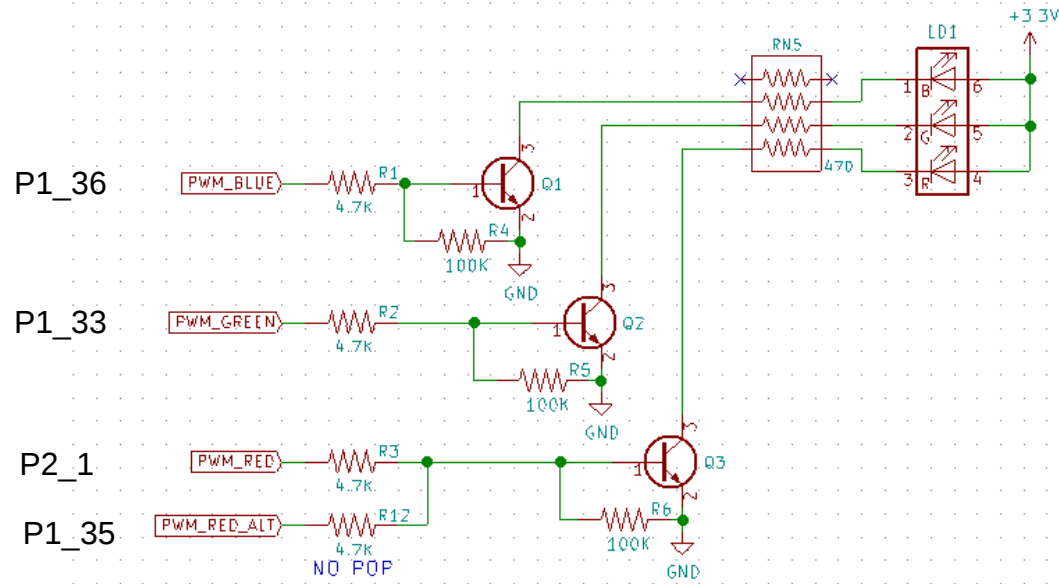
USER BUTTON

BaconBits ADC thumbwheel



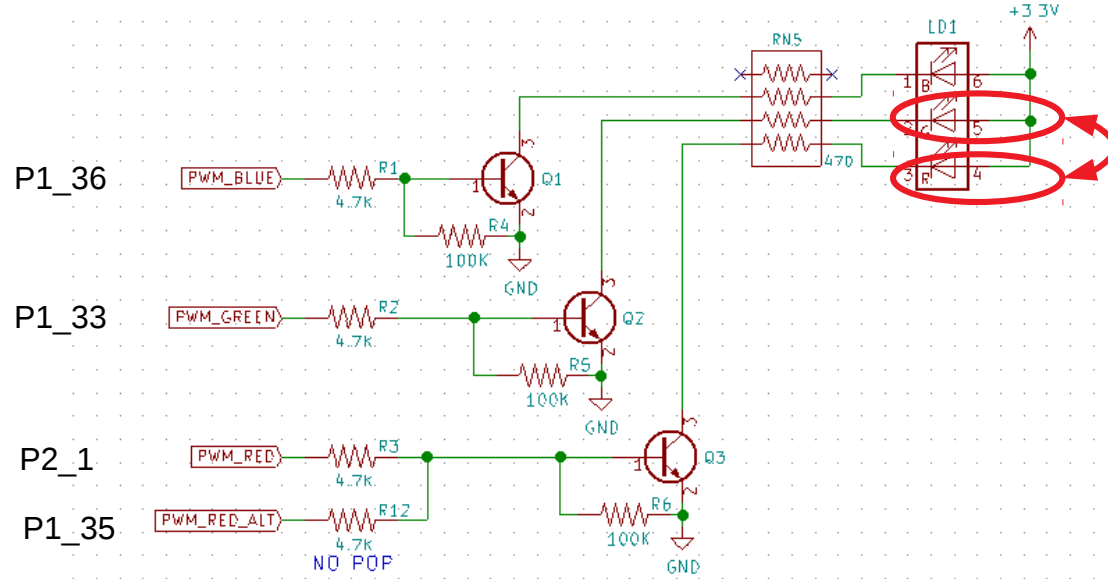
THUMBWHEEL

BaconBits RGB LED



RGB LED

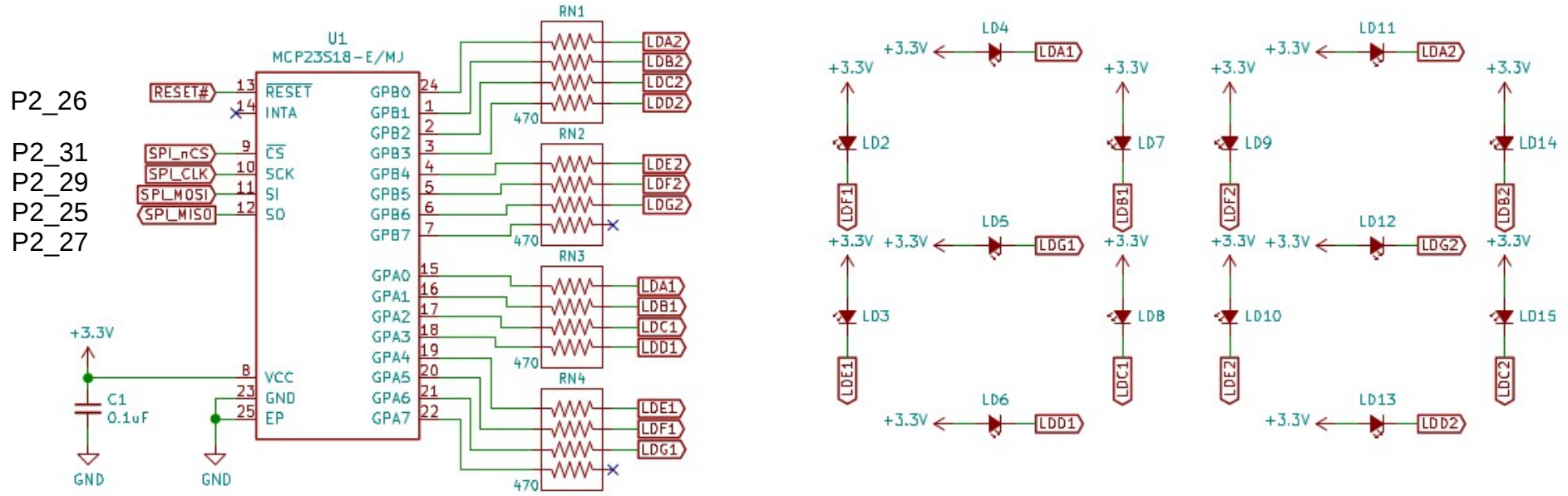
BaconBits RGB LED



RGB LED

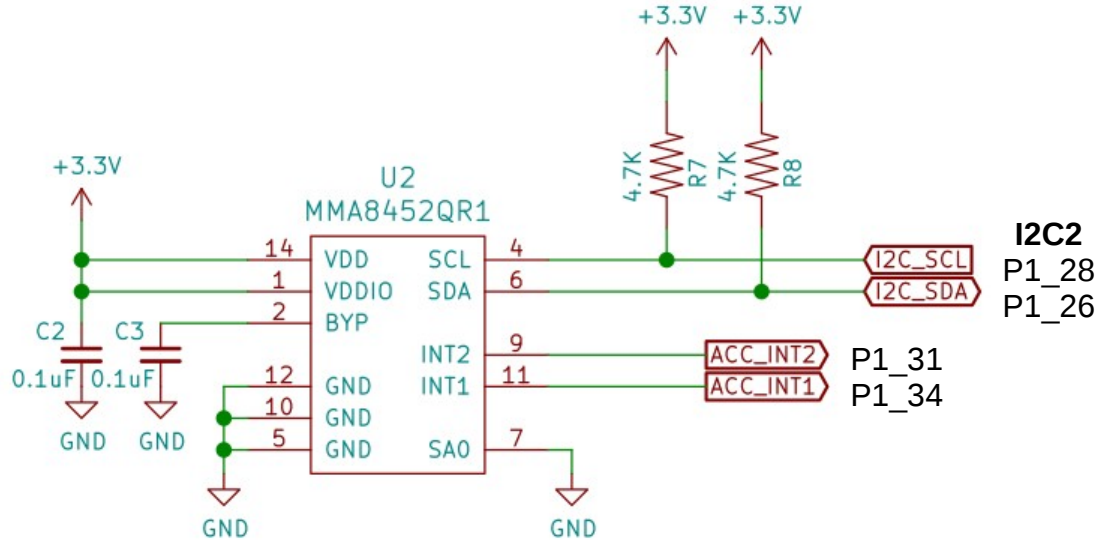


BaconBits SPI 7-segment display



EMULATED 7 SEGMENTS

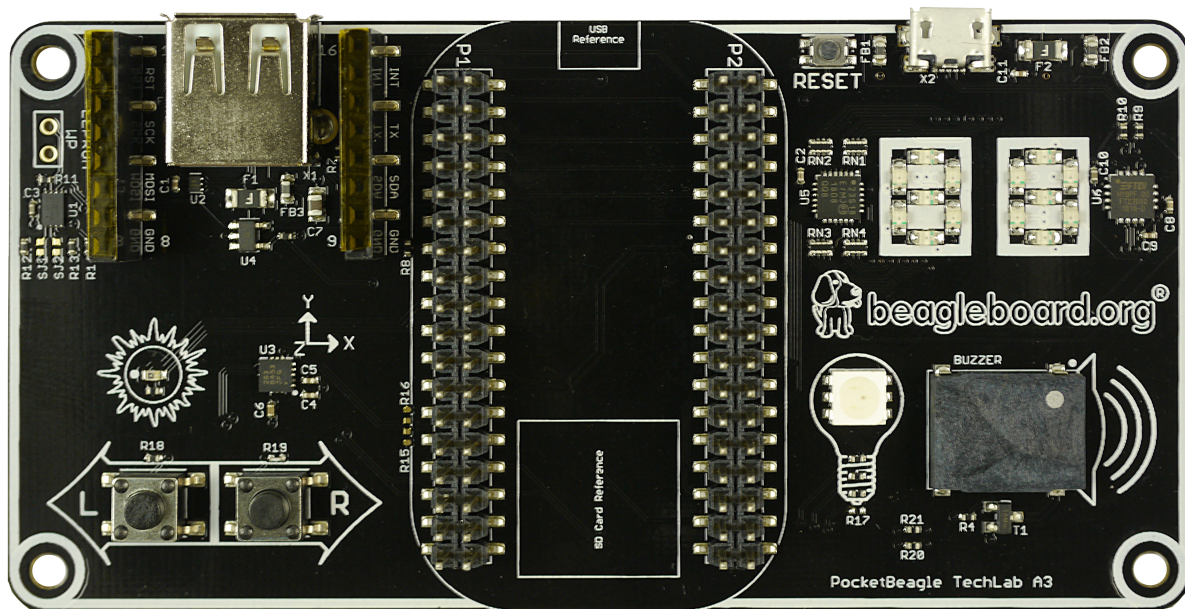
BaconBits I2C accelerometer



ACCELEROMETER

PocketBeagle TechLab Cape

- Designed to be compatible with BaconBits
- beagleboard.org/techlab

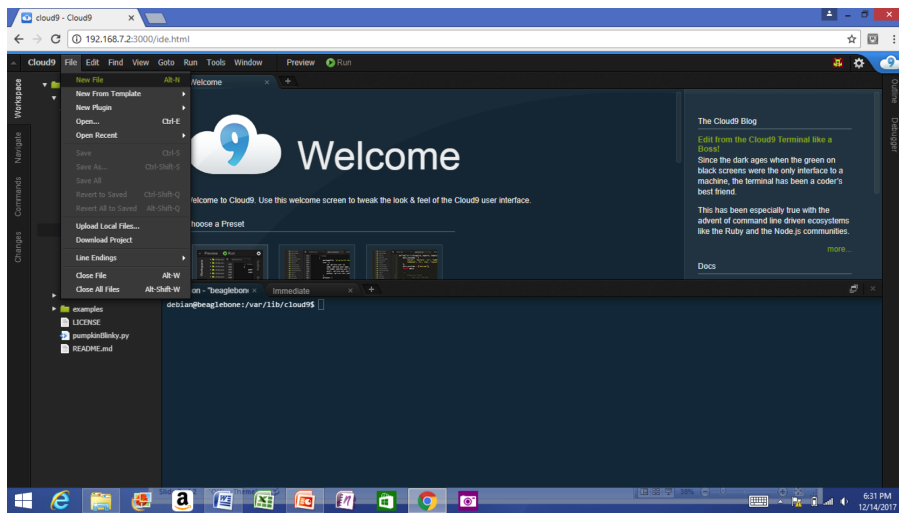


Developer experience

- Customized Debian images – bbb.io/latest
- Self-hosted tools for ARMs and PRU
- Libraries for various high-level languages
- Scripts for common tasks
- Sources for bootloader, device tree, etc.
- Servers for network-based development

Single cable development

- Power, network, develop
- You can add a network and power many other ways



Some work in progress

- Add proxy for various services (in Buster IoT images today)
- Integrate common web-based WiFi provisioning
 - SeeedStudio BeagleBone Green Wireless ships with 'wifidog' → we will unify approach
- Cross-platform distro installer app
 - See USB NETCONSOLE presentation
- Support for Grove modules and mikroBus clicks
 - Focus on device-tree overlays and kernel patches
- Integration alignment with complete domain solutions
 - Intelligent Agent Replicape/Revolve, Bela Mini, BeagleLogic, etc.
- Improved and integrated PRU examples
- Move to distro friendly approaches for customizations

Download image



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https://beagleboard.org/latest-images

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BeagleBoard.org Latest Firmware Images

Download the latest firmware for your BeagleBoard, BeagleBoard-xM, BeagleBoard-X15, BeagleBone, BeagleBone Black, BeagleBone Black Wireless, BeagleBone Blue, SeeedStudio BeagleBone Green, SeeedStudio BeagleBone Green Wireless, SanCloud BeagleBone Enhanced, element14 BeagleBone Black Industrial, Arrow BeagleBone Black Industrial, Mentorel BeagleBone uSomIQ, Neuromeka BeagleBone Air, or PocketBeagle

 beagleboard.org®

See the [Getting Started guide](#) and the [community wiki page](#) for hints on loading these images.

Recommended Debian Images

Stretch IoT (non-GUI) for [BeagleBone](#) and [PocketBeagle](#) via microSD card

- ▶ [Debian 9.2 2017-10-10 4GB SD IoT image](#) for [PocketBeagle](#), [BeagleBone](#), [BeagleBone Black](#), [BeagleBone Black Wireless](#), [BeagleBone Blue](#), [SeeedStudio BeagleBone Green](#), [SeeedStudio BeagleBone Green Wireless](#), [SanCloud BeagleBone Enhanced](#), [element14 BeagleBone Black Industrial](#), [Arrow BeagleBone Black Industrial](#) and [Mentorel BeagleBone uSomIQ](#) - more info - `bmap - sha256sum: be1eac7a5e526930155520215329a6c39071b82199c0745c300e68b7e6c7180b`

Stretch for [BeagleBone](#) via microSD card

- ▶ [Debian 9.1 2017-08-31 4GB SD LXQT image](#) for [BeagleBone](#), [BeagleBone Black](#), [BeagleBone Black Wireless](#), [BeagleBone Blue](#), [SeeedStudio BeagleBone Green](#), [SeeedStudio BeagleBone Green Wireless](#), [SanCloud BeagleBone Enhanced](#), [element14 BeagleBone Black Industrial](#), [Arrow BeagleBone Black Industrial](#) and [Mentorel BeagleBone uSomIQ](#) - more info - `bmap - sha256sum: bc8292d97458987481d45da025ef9868b8ccf8477a72f11b541bf97d329a6d7e`

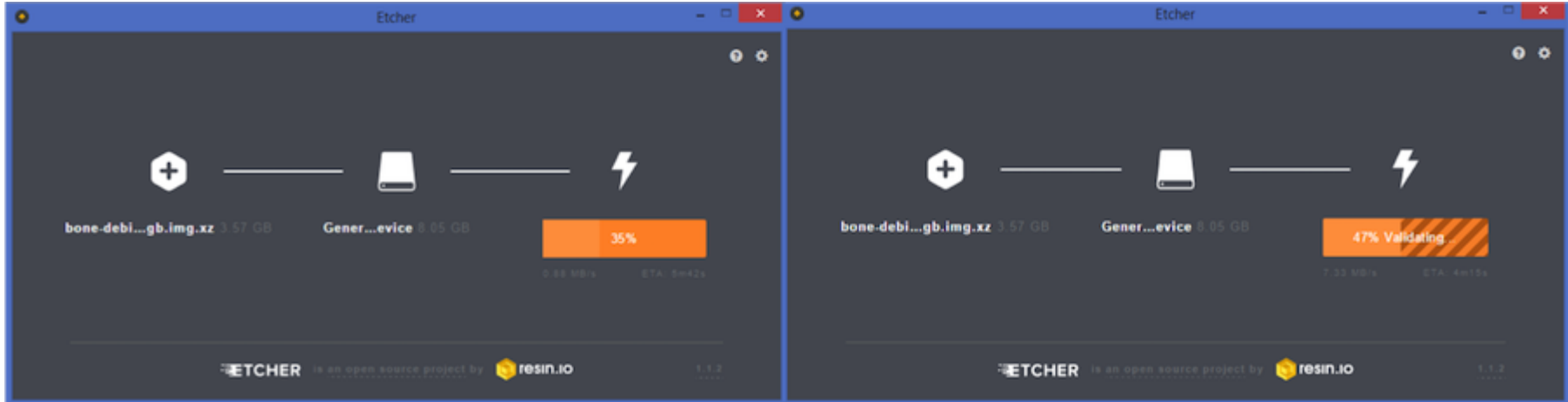
Jessie for [SeeedStudio BeagleBone Green Wireless](#) via microSD card

- ▶ [Debian 8.6 2016-11-06 4GB SD SeeedStudio IoT image](#) for [SeeedStudio BeagleBone Green Wireless](#) - more info - `bmap - sha256sum: 48582b8a1a134679ff324eacc1e0b4af6f2cdabfb56dafb6b932fe11129b404f`

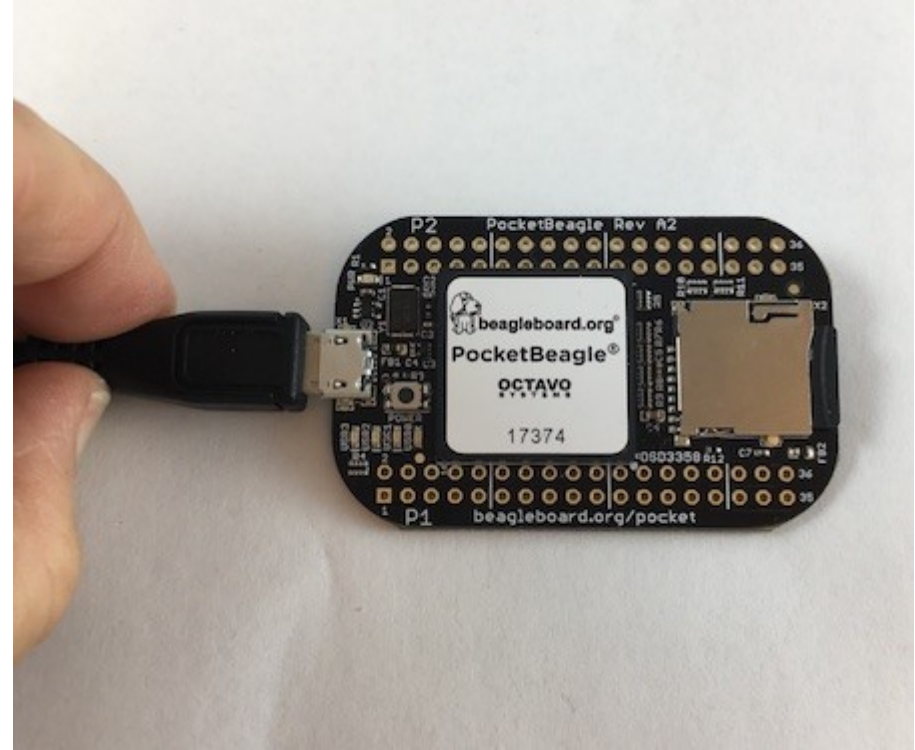
Stretch for [BeagleBoard-X15](#) via microSD card



Write image to microSD with Etcher



Insert microSD and boot






Connect to the USB network

Getting started with Beagle x

file:///Volumes/BEAGLEBONE/START.htm



Start ↓ Discover Boards ↓ Learn ↓ Explore ↓ Collaborate ↓ Google Custom Search Search

Start your Beagle

Beagles are tiny computers with the capability of modern systems, without the bulk, expense, or noise. Read the step-by-step getting started tutorial below to begin developing with your Beagle in minutes.

For user supplied tips on getting started, visit the eLinux (or other) community wiki pages:

- BeagleBoard ⚡
- BeagleBoard-xM ⚡
- BeagleBoard-X15 ⚡
- BeagleBone ⚡
- BeagleBone Black ⚡
- BeagleBone Black Wireless ⚡
- BeagleBone Blue ⚡
- SeedStudio BeagleBone Green ⚡
- SeedStudio BeagleBone Green Wireless ⚡
- SanCloud BeagleBone Enhanced ⚡
- NeuroMeka BeagleBone Air ⚡

If any step fails, it is recommended to update to the latest software image to use the instructions below.

Step 1 ▶ Power and boot

Most Beagles include a USB cable, providing a convenient way to provide both power to your Beagle and connectivity to your computer. If you provide your own, ensure it is of good quality. You'll connect the "type-B" plug ⚡ of the USB cable to your Beagle and the "type-A" plug to your computer. Note that BeagleBoard-X15 must always be powered instead by a 12V adapter with a barrel jack.

Alternatively, for Beagles other than BeagleBoard-X15 and BeagleBone Blue that require 12V, you can utilize a 5V adapter connected to the barrel jack.

Getting started with Beagle x

192.168.6.2:3000

Step 2 ▶ Enable a network connection

If connected via USB, a network adapter should show up on your computer. Your Beagle should be running a DHCP server that will provide your computer with an IP address of either 192.168.7.1 or 192.168.6.1, depending on the type of USB network adapter supported by your computer's operating system. Your Beagle will reserve 192.168.7.2 or 192.168.6.2 for itself.

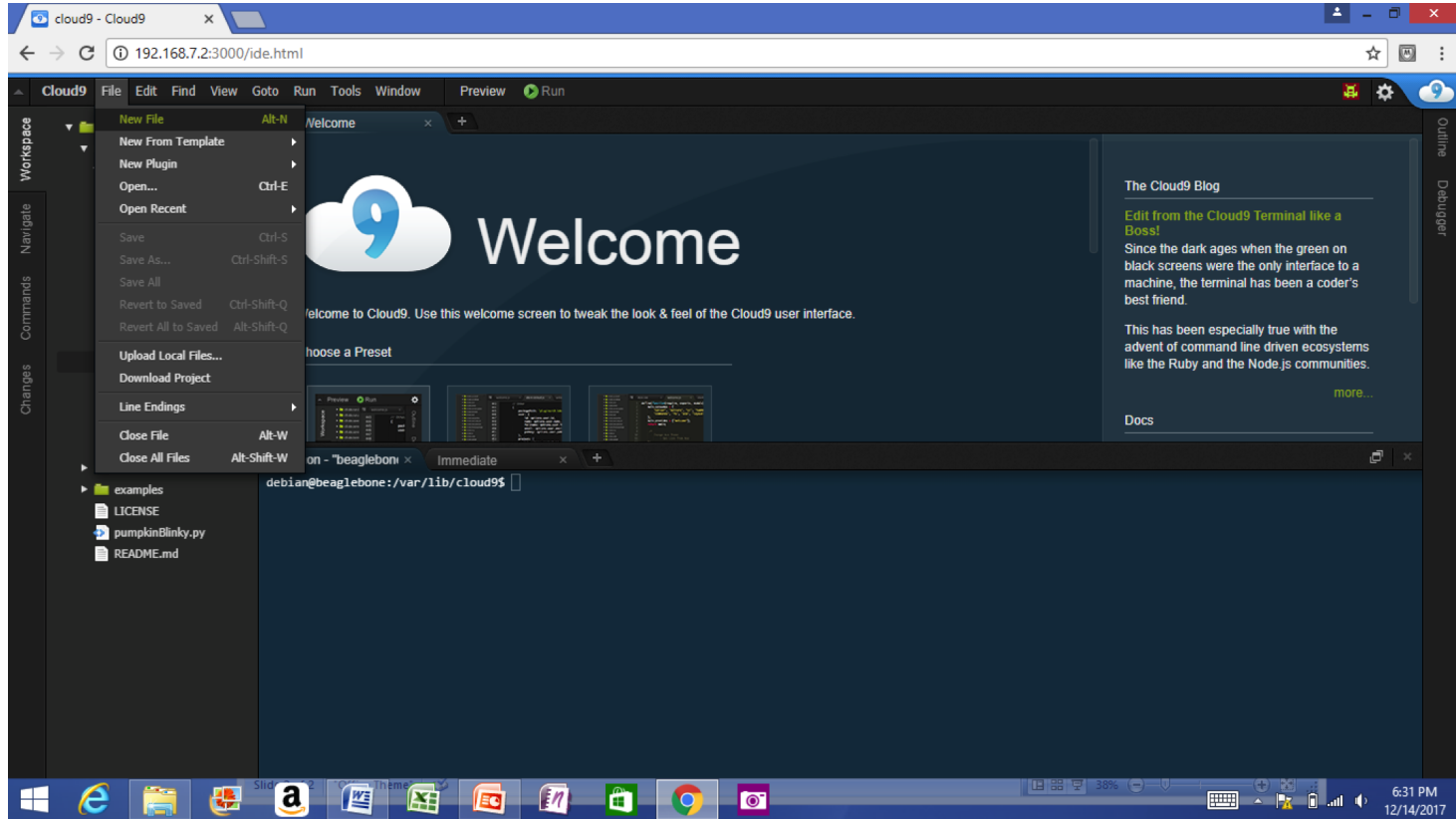
If your Beagle includes WiFi, an access point called "BeagleBone-XXXX" where "XXXX" varies between boards. The access point password defaults to "BeagleBone". Your Beagle should be running a DHCP server that will provide your computer with an IP address in the 192.168.8.x range and reserve 192.168.8.1 for itself.

If your Beagle is connected to your local area network (LAN) via either Ethernet or WiFi, it will utilize mDNS ⚡ to broadcast itself to your computer. If your computer supports mDNS, you should see your Beagle as beaglebone.local. Non-BeagleBone boards will utilize alternate names. Multiple BeagleBone boards on the same network will add a suffix such as beaglebone-2.local.

The below table summarizes the typical addresses and should dynamically update to indicate an active connection. Note that you must load this page without HTTPS security for the automatic detection to work.

IP Address	Connection Type	Operating System(s)	Status
192.168.7.2	USB	Windows	Inactive
192.168.6.2	USB	Mac OS X, Linux	Active ⚡
192.168.8.1	WiFi	all	Inactive
beaglebone.local	all	mDNS enabled	Active ⚡
beaglebone-2.local	all	mDNS enabled	Inactive

Open the IDE



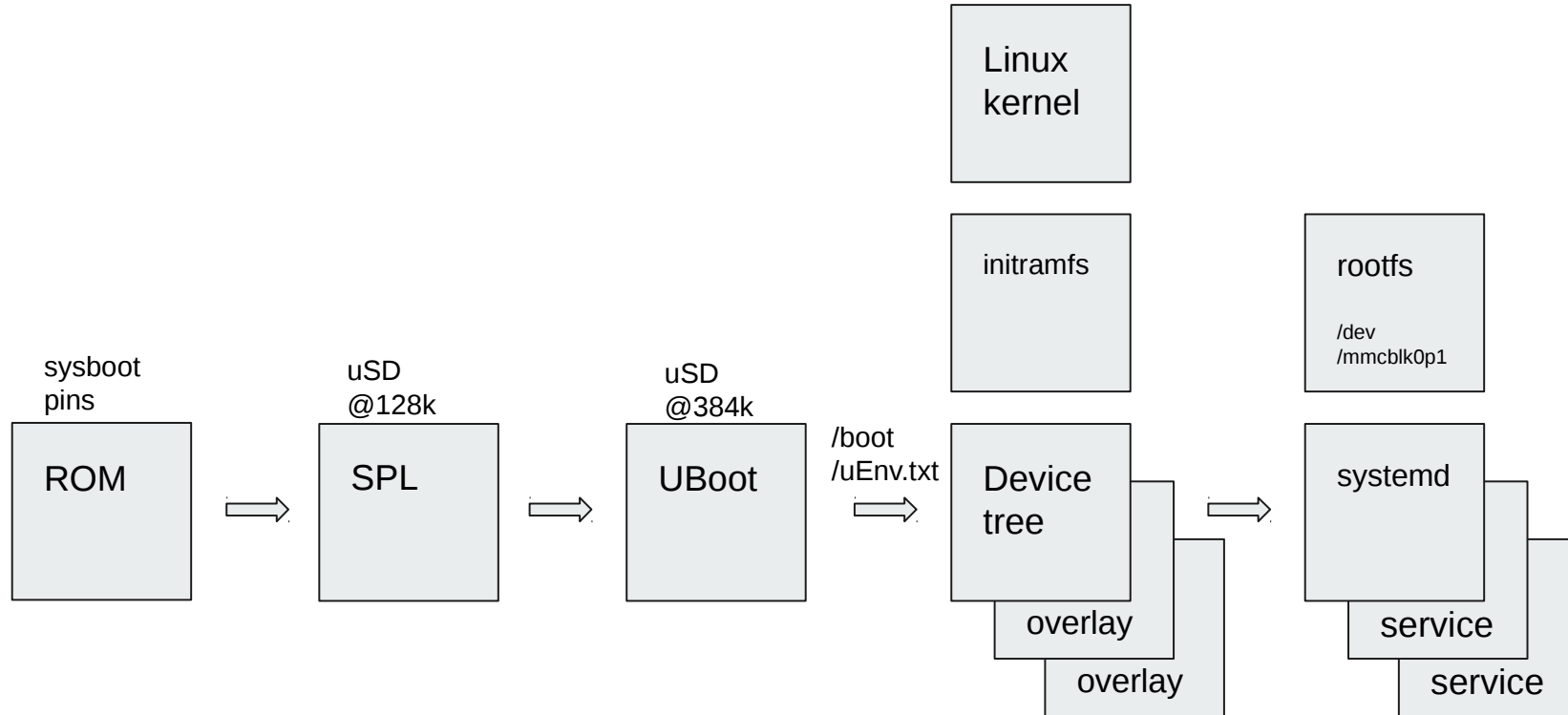
USB gadgets

- Linux name for device/slave drivers
 - ie., when not host
- USB devices have “classes”
 - Mass storage
 - Camera
 - Audio
 - Printer
 - “HID” or human-interface device like mouse and keyboard
 - Communications

USB gadgets

- Default image USB gadgets
 - Virtual mass storage
 - Serves you up README.htm
 - Virtual serial
 - Provides access to console after kernel boot
 - Virtual network
 - Enables access to ssh and web servers

Boot summary



In Linux, everything becomes a file

- Much to learn
 - I'm used to microcontrollers: just give me the datasheet with register definitions and set me free!
- Training on boot & device drivers useful
 - Often geared more at system bring-up
 - What about the everyday user?
 - Where is that abstraction benefit?
- Let's just walk a working system!

What is the baseline?

<http://refspecs.linuxfoundation.org/lsb.shtml>

- Every Linux system may be customized
 - This is the nature of open source
 - Stuff still needs to work together
- The Linux Standard Base
 - Umbrella for various Linux Foundation groups
 - A specification and a testkit
 - Documents typical libraries, functions and files expected to be found by the developer

lsb_release

```
debian@beaglebone:~$ sudo apt install -y lsb
debian@beaglebone:~$ lsb_release -a
No LSB modules are available.
Distributor ID: Debian
Description:    Debian GNU/Linux 9.5 (stretch)
Release:       9.5
Codename:      stretch
```

Filesystem Hierarchy Standard

<http://www.pathname.com/fhs/>

- /tmp: temporary files
- /var: data that is changes at run-time
- /proc: "information from processes" (virtual)
- /sys: "system filesystem" (virtual)
- /dev: device files
- /media: mount point for removable media
- /lost+found: data without directory entry
- /mnt: mount point for temporary mounted file systems
- /opt: add-on application software packages

/proc

```
debian@beaglebone:~$ ls /proc
1      1692  22   3354  878  990      fb      misc      sysvipc
10     17    23   3362  89   apm     filesystems  modules  thread-self
11     18    2370 34    9      asound  fs        mounts   timer_list
1110   1857  2375 4     90     buddyinfo  interrupts  mtd      tty
1112   19    2377 6     91     bus      iomem     net      uptime
1119   1951  2379 69    913    cgroups  ioports   pagetypeinfo  version
1150   1964  24    7     918    cmdline  irq       partitions  vmallocinfo
1151   2     25    70    92     config.gz  kallsyms  pvr       vmstat
1152   20    26    71    93     consoles  keys      sched_debug  zoneinfo
12     21    27    72    945    cpu      key-users  schedstat
1215   2107  28    73    951    cpuinfo  kmsg     self
1247   2120  29    74    959    crypto   kpagecgroup  slabinfo
13     2149  30    8     973    devices  kpagecount  softirqs
1440   2152  31    800   977    device-tree  kpageflags  stat
15     2153  32    820   980    diskstats  loadavg    swaps
159    2155  33    821   983    driver    locks     sys
16     2173  3353  858   984    execdomains  meminfo   sysrq-trigger
```

/proc/cpuinfo

```
debian@beaglebone:~$ cat /proc/cpuinfo
processor           : 0
model name        : ARMv7 Processor rev 2 (v7l)
BogoMIPS         : 995.32
Features          : half thumb fastmult vfp edsp thumbee neon vfpv3
                  tls vfpd32
CPU implementer   : 0x41
CPU architecture : 7
CPU variant      : 0x3
CPU part         : 0xc08
CPU revision     : 2

Hardware         : Generic AM33XX (Flattened Device Tree)
Revision        : 0000
Serial          : 1741GPB42934
```


The file interface abstraction

- What can I do with files?
 - open, read, write, close, delete
 - What is an "ioctl"?
 - What is "mmap"?
- What is a virtual file system?
 - Looks like a file, but executes code in the kernel
 - Not really storing anything to media
 - A bit like a "ram disk"

Kernel.org documentation

<http://www.kernel.org/doc/>

- Documentation extracted from the Linux kernel and mirrored on the web where Google can find it:
 - Documentation - Text files in the kernel source tarball's Documentation subdirectory
 - htmldocs - Kernel Documentation maintained in docbook format (output of "make htmldocs")
 - Menuconfig - help text for each kernel configuration option (from kconfig source)
 - README various README files scattered around Linux kernel source
 - RFC - List of IETF RFCs referred to by kernel source files. Links to both the text of the RFC and the source files that refer to it
 - Output of kernel's "make help"
- Standards documents applicable to the Linux kernel
- Other web pages containing kernel documentation
- Translations to other languages
- Documentation on memory management
- Miscellaneous

Kernel Application Binary Interface

<http://www.kernel.org/doc/Documentation/ABI/>

- Low-level kernel interface from "userland"
- Status of interface
 - Stable
 - Encouraged to use freely
 - Guaranteed for at least two years
 - Testing
 - Mostly complete, but might change
 - Let developers know how you are using
 - Where you'll find most of the good stuff
 - Obsolete
 - Scheduled for removal
 - Removed

Kernel Application Binary Interface

<http://www.kernel.org/doc/Documentation/ABI/>

- Types of interfaces
 - Syscalls
 - Trap interface with IDs
 - May be possible to have a direct entry
 - SYSFS
 - Virtual file system
 - See also DEBUGFS and CONFIGFS



Syscalls

<http://www.kernel.org/doc/man-pages/online/pages/man2/syscalls.2.html>

- open/read/write/lseek/close/unlink
- ioctl
- mknod
- fork/select/poll/...
- mkdir/...
- mount/umount
- mmap



What is SYSFS?

- Virtual file system that exposes drivers to userspace
- `mount | grep sysfs`
 - `sysfs on /sys type sysfs (rw,nosuid,nodev,noexec,relatime)`
- `/sys/devices` - driver hierarchy
- `/sys/bus` - symbolic links to bus owners
- `/sys/class` - common interfaces
- `/sys/block` - block interface
- How about some examples?

/sys/module

<http://www.kernel.org/doc/Documentation/ABI/stable/sysfs-module>

- /sys/module/MODULENAME
 - .../parameters: options you can provide
 - .../refcnt: number of times in use

```
debian@beaglebone:~$ ls /sys/module
8250                fb                  lockd               pruss               sysrq               usb_f_ecm
apparmor            firmware_class     mma8452            pruss_intc         tcp_cubic           usb_f_mass_storage
auth_rpcgss        fscrypto           mmcbk              pruss_soc_bus     tda18271           usb_f_rndis
block              fuse               module             pvrsrvkm           tda827x            usbhid
bone_capemgr       hid                mt20xx             r8188eu           tda8290            usb_storage
can                hid_logitech       netpoll            random             tda9887            u_serial
cec                hid_logitech_hidpp nf_contrack        rc_core            tea5761             vt
cfg80211           i2c_algo_bit      nf_contrack_ipv4  rcupdate           tea5767             watchdog
configfs           ima                nf_defrag_ipv4    rcutree            ti_cpsw             wireguard
cpufreq            iptable_filter    nf_nat             rfskill            tpm                 workqueue
cpuidle            iptable_mangle    nf_nat_ipv4       rng_core            tuner_simple        xc4000
cryptomgr          iptable_nat       nfs                scsi_mod           tuner_xc2028        xc5000
dns_resolver       ip_tables         nfs_layout_nfsv41_files sdhci              ubi                  xhci_hcd
drm                ipv6               nfsv4              snd                 ubifs                x_tables
drm_kms_helper     ir_kbd_i2c        omapdrm            snd_pcm            udl                  xz_dec
dvb_core           kernel             omap_mailbox       snd_timer          u_ether              zswap
dynamic_debug      keyboard          onenand            spidev             uinput
eeprom_93cx6       leds_pwm           overlay            spurious           uio
ehci_hcd           libahci           pinctrl_mcp23s08  srcutree           uio_pdrv_genirq
etnaviv            libata            printk             sunrpc             usbcore
evdev              libcomposite      pru_rproc          suspend            usb_f_acm
```




/sys/class/leds

<https://www.kernel.org/doc/Documentation/ABI/testing/sysfs-class-led>

- /sys/class/leds/LED
 - .../brightness: 0-max_brightness, >0 = on
 - .../max_brightness: default is 255
 - .../trigger: triggers available from kernel
 - .../inverted: invert on/off state

```
debian@beaglebone:~$ ls /sys/class/leds
beaglebone:green:usr0  techlab::blue  techlab::seg1  techlab::seg13  techlab::seg3  techlab::seg7
beaglebone:green:usr1  techlab::green  techlab::seg10  techlab::seg14  techlab::seg4  techlab::seg8
beaglebone:green:usr2  techlab::red    techlab::seg11  techlab::seg15  techlab::seg5  techlab::seg9
beaglebone:green:usr3  techlab::seg0  techlab::seg12  techlab::seg2   techlab::seg6
```



/sys/class/gpio

<http://www.kernel.org/doc/Documentation/ABI/testing/sysfs-gpio>

- Must be explicitly exported to userspace and not claimed by kernel code
- /sys/class/gpio
 - .../export: asks the kernel to export a GPIO to userspace
 - .../unexport: to return a GPIO to the kernel
 - .../gpioN: for each exported GPIO #N
 - .../value: always readable, writes fail for input GPIOs
 - .../direction: r/w as: in, out (low); write: high, low
 - .../edge: r/w as: none, falling, rising, both
 - .../gpiochipN: for each gpiochip; #N is its first GPIO
 - .../base: (r/o) same as N
 - .../label: (r/o) descriptive, not necessarily unique
 - .../ngpio: (r/o) number of GPIOs; numbered N to N + (ngpio - 1)

```
debian@beaglebone:~$ ls /sys/class/gpio
```

```
export  gpio114  gpio13  gpio20  gpio30  gpio42  gpio47  gpio58  gpio7  gpiochip0  unexport
gpio110  gpio115  gpio14  gpio23  gpio31  gpio43  gpio5  gpio59  gpio86  gpiochip32
gpio111  gpio116  gpio15  gpio26  gpio4  gpio44  gpio50  gpio60  gpio87  gpiochip496
gpio112  gpio117  gpio19  gpio27  gpio40  gpio45  gpio52  gpio64  gpio88  gpiochip64
gpio113  gpio12  gpio2  gpio3  gpio41  gpio46  gpio57  gpio65  gpio89  gpiochip96
```

On-chip peripherals (OCP)

```
debian@beaglebone:~$ ls /sys/devices/platform/ocp
40300000.ocmcram 480c8000.mailbox 53100000.sham ocp:P1_32_pinmux ocp:P2_20_pinmux
44e07000.gpio 480ca000.spinlock 53500000.aes ocp:P1_33_pinmux ocp:P2_22_pinmux
44e09000.serial 4819c000.i2c 56000000.sgx ocp:P1_34_pinmux ocp:P2_24_pinmux
44e0b000.i2c 481a0000.spi driver_override ocp:P1_35_pinmux ocp:P2_25_pinmux
44e0d000.tscadc 481a8000.serial modalias ocp:P1_36_pinmux ocp:P2_27_pinmux
44e35000.wdt 481ac000.gpio ocp:cape-universal ocp:P2_01_pinmux ocp:P2_28_pinmux
44e3e000.rtc 481ae000.gpio ocp:l4_wkup@44c00000 ocp:P2_02_pinmux ocp:P2_29_pinmux
47400000.usb 481cc000.can ocp:P1_02_pinmux ocp:P2_03_pinmux ocp:P2_30_pinmux
48022000.serial 481d0000.can ocp:P1_04_pinmux ocp:P2_04_pinmux ocp:P2_31_pinmux
48024000.serial 48300000.epwmss ocp:P1_06_pinmux ocp:P2_05_pinmux ocp:P2_32_pinmux
4802a000.i2c 48302000.epwmss ocp:P1_08_pinmux ocp:P2_06_pinmux ocp:P2_33_pinmux
48030000.spi 48304000.epwmss ocp:P1_10_pinmux ocp:P2_07_pinmux ocp:P2_34_pinmux
48042000.timer 48310000.rng ocp:P1_12_pinmux ocp:P2_08_pinmux ocp:P2_35_pinmux
48044000.timer 49000000.edma ocp:P1_20_pinmux ocp:P2_09_pinmux of_node
48046000.timer 49800000.tptc ocp:P1_26_pinmux ocp:P2_10_pinmux power
48048000.timer 49900000.tptc ocp:P1_28_pinmux ocp:P2_11_pinmux subsystem
4804a000.timer 49a00000.tptc ocp:P1_29_pinmux ocp:P2_17_pinmux uevent
4804c000.gpio 4a326004.pruss-soc-bus ocp:P1_30_pinmux ocp:P2_18_pinmux
48060000.mmc 4c000000.emif ocp:P1_31_pinmux ocp:P2_19_pinmux
```

Reading events

- TBD

Instantiating a device: .dts example

```
&i2c0 {  
    pinctrl-names = "default";  
    pinctrl-0 = <&i2c0_pins>;  
  
    status = "okay";  
    clock-frequency = <400000>;  
  
    tps: tps@24 {  
        reg = <0x24>;  
    };  
  
    baseboard_eeprom: baseboard_eeprom@50 {  
        compatible = "at,24c256";  
        reg = <0x50>;  
  
        #address-cells = <1>;  
        #size-cells = <1>;  
        baseboard_data: baseboard_data@0 {  
            reg = <0 0x100>;  
        };  
    };  
};
```

Phandle
(reference
to label)

Pin muxing configuration
(routing to external package pins)

Enabling this device, otherwise ignored
Node property: frequency

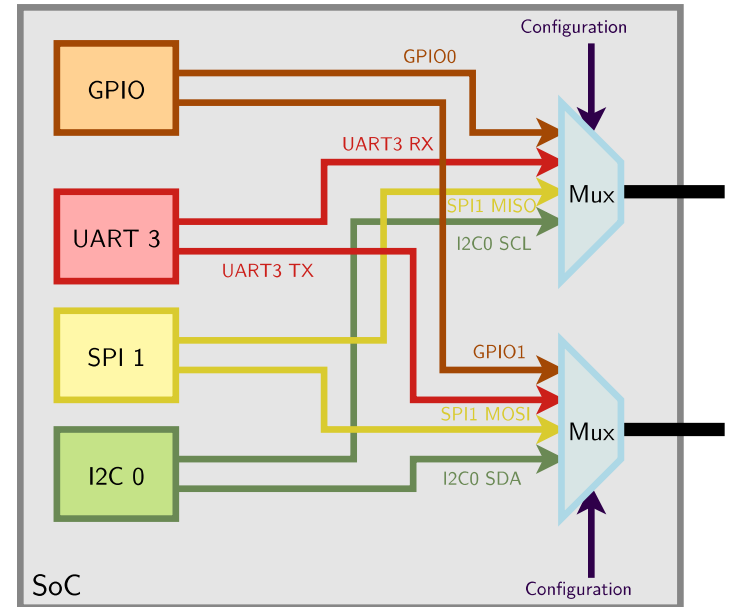
List of devices on
i2c0

I2C bus identifier

From arch/arm/boot/dts/am335x-boneblue.dts

Pin multiplexing

- Modern SoCs have too many hardware blocks compared to physical pins exposed on the chip package.
- Therefore, pins have to be multiplexed
- Pin configurations are defined in the Device Tree
- Correct pin multiplexing is mandatory to make a device work from an electronic point of view.



Device Tree

- See kernel documentation for bindings
 - [devicetree/bindings/eeprom/eeprom.txt](#)
- Local copies enable you to extend on the fly
 - [/opt/source/dtb-4.9-ti](#)
 - [/opt/source/bb.org-overlays](#)
- Overlays loaded in u-boot, but also possible via kernel configs

DT pin definitions

```
&am33xx_pinmux {  
    ...  
    i2c0_pins: pinmux_i2c0_pins {  
        pinctrl-single,pins = <  
            AM33XX_IOPAD(0x988, PIN_INPUT_PULLUP | MUX_MODE0) /* (C17) I2C0_SDA.I2C0_SDA */  
            AM33XX_IOPAD(0x98c, PIN_INPUT_PULLUP | MUX_MODE0) /* (C16) I2C0_SCL.I2C0_SCL */  
        >;  
    };  
    ...  
};  
...  
&i2c0 {  
    pinctrl-names = "default";  
    pinctrl-0 = <&i2c0_pins>;  
  
    status = "okay";  
    clock-frequency = <400000>;  
    ...  
};
```

Register offset corresponding to a given package pin

Configures the pin: input, output, drive strength, pull up/down...

Allows to select a given SoC signal

Package pin name

SoC signal name

From arch/arm/boot/dts/am335x-boneblue.dts

DT: matching devices and drivers

Platform drivers are matched with platform devices that have the same `compatible` property.

```
static const struct of_device_id omap_i2c_of_match[] = {
    {
        .compatible = "ti,omap4-i2c",
        .data = &omap4_pdata,
    },
    {
        ...
    };
    ...
static struct platform_driver omap_i2c_driver = {
    .probe          = omap_i2c_probe,
    .remove         = omap_i2c_remove,
    .driver         = {
        .name       = "omap_i2c",
        .pm         = OMAP_I2C_PM_OPS,
        .of_match_table = of_match_ptr(omap_i2c_of_match),
    },
};
```

From `drivers/i2c/busses/i2c-omap.c`



config-pin

<https://github.com/beagleboard/bb.org-overlays - tools/beaglebone-universal-io>

```
debian@beaglebone:~$ config-pin -i p1.36
Pin name: P1_36
Function if no cape loaded: pwm
Function if cape loaded: default gpio gpio_pu gpio_pd
gpio_input spi_sclk pwm pruout pruin
Function information: ehrpwm0a default gpio3_14 gpio3_14
gpio3_14 gpio3_14 spi1_sclk ehrpwm0a pru0_out0 pru0_in0
Kernel GPIO id: 110
PRU GPIO id: 142
debian@beaglebone:~$ config-pin -q p1.36
P1_36 Mode: default Direction: in Value: 0
debian@beaglebone:~$ config-pin p1.36 pruout
debian@beaglebone:~$ config-pin -q p1.36
P1_36 Mode: pruout
```

show-pins.pl

- `perl /opt/scripts/device/bone/show-pins.pl -v`

Enabling PRU

- 2 possible drivers: remoteproc or uio
- Enabled via device tree at boot
 - Different systems might have different defaults

mikroBus Click usage

- See bbb.io/pbmb
- Supported with device-tree overlays loaded in u-boot

Demonstrations

- BaconBits demo
-

Some current projects

- Bela Mini
- PocketPilot

Contributions and issues

- Cape/add-on support
 - <https://github.com/beagleboard/bb.org-overlays>
- Image deltas
 - <https://github.com/beagleboard/image-builder>
- In-system examples
 - <https://github.com/beagleboard/bone101>

Questions?



Thank you!

